### V200-18-E6B Snap-in I/O Module

The V200-18-E6B plugs directly into the back of compatible	<u>Features</u>
	<ul> <li>18 isolated digital in includes 2 shaft enc</li> </ul>
creating a self-	<ul> <li>15 isolated relay out</li> </ul>
contained PLC unit with a local I/O	<ul> <li>2 isolated pnp/npn ( 2 high-speed output</li> </ul>
configuration.	<ul> <li>5 analog inputs, incl</li> </ul>

- puts configurable to type pnp/npn (source/sink), oder inputs.
- tputs.
- source/sink) transistor outputs, includes s.
- udes 2 inputs configurable to RTD or thermocouple. 2 isolated analog outputs.
- Before using this product, it is the responsibility of the user to read and understand this document and any accompanying documentation.
- All examples and diagrams shown herein are intended to aid understanding, and do not guarantee operation. Unitronics accepts no responsibility for actual use of this product based on these examples.
- Please dispose of this product in accordance with local and national standards and regulations.
- Only qualified service personnel should open this device or carry out repairs.

# User safety and equipment protection guidelines

This document is intended to aid trained and competent personnel in the installation of this equipment as defined by the European directives for machinery, low voltage, and EMC. Only a technician or engineer trained in the local and national electrical standards should perform tasks associated with the device's electrical wiring.

Symbols are used to highlight information relating to the user's personal safety and equipment protection throughout this document. When these symbols appear, the associated information must be read carefully and understood fully.

Symbol	Meaning	Description
<u>s</u>	Danger	The identified danger causes physical and property damage.
$\triangle$	Warning	The identified danger can cause physical and property damage.
Caution	Caution	Use caution.

Â	<ul> <li>Failure to comply with appropriate safety guidelines can result in severe personal injury or property damage. Always exercise proper caution when working with electrical equipment.</li> </ul>
	<ul> <li>Check the user program before running it.</li> </ul>
	<ul> <li>Do not attempt to use this device with parameters that exceed permissible levels.</li> </ul>
<u> </u>	<ul> <li>Install an external circuit breaker and take appropriate safety measures against short- circuiting in external wiring.</li> </ul>
	<ul> <li>To avoid damaging the system, do not connect / disconnect the device when the power is on.</li> </ul>

Caution

Ascertain that terminal blocks are properly secured in place.

# **Environmental Considerations**

È	<ul> <li>Do not install in areas with: excessive or conductive dust, corrosive or flammable gas, moisture or rain, excessive heat, regular impact shocks or excessive vibration.</li> </ul>
Â	<ul> <li>Provide proper ventilation by leaving at least 10mm of space between the top and bottom edges of the device and the enclosure walls.</li> </ul>
<u>/•</u> \	<ul> <li>Do not place in water or let water leak onto the unit.</li> </ul>
	<ul> <li>Do not allow debris to fall inside the unit during installation.</li> </ul>

Wiring	
) \$	<ul> <li>Do not touch live wires.</li> </ul>
Â	<ul> <li>Unused pins should not be connected. Ignoring this directive may damage the device.</li> <li>Do not connect the 'Neutral' or 'Line' signal of the 110/220VAC to the device's 0V pin.</li> <li>Double-check all wiring before turning on the power supply.</li> </ul>

### Wiring Procedures

Use crimp terminals for wiring; use 26-12 AWG wire (0.13mm<sup>2</sup>-3.31mm<sup>2</sup>) for all wiring purposes.

- 1. Strip the wire to a length of 7±0.5mm (0.250–0.300 inches).
- 2. Unscrew the terminal to its widest position before inserting a wire.
- 3. Insert the wire completely into the terminal to ensure that a proper connection can be made.
- 4. Tighten enough to keep the wire from pulling free.
- To avoid damaging the wire, do not exceed a maximum torque of 0.5 N·m (5 kgf·cm).
- Do not use tin, solder, or any other substance on stripped wire that might cause the wire strand to break.
- Install at maximum distance from high-voltage cables and power equipment.

### I/O Wiring—General

- Input or output cables should not be run through the same multi-core cable or share the same wire.
- Allow for voltage drop and noise interference with input lines used over an extended distance. Use wire that is properly sized for the load.

# **Digital Inputs**

Each group of 9 inputs has a common signal. Each group can be used as either pnp (source) or npn (sink), when appropriately wired as shown in the following figures.

- Inputs I0 and I2 can be used as normal digital inputs, as high-speed counters, or as part of a shaft encoder.
- Inputs I1 and I3 can be used as normal digital inputs, as high-speed counter resets, or as part of a shaft encoder.



Inputs I0, I1, and I2, I3 can be used as shaft encoders as shown below.



# **Digital Outputs**

# Wiring Power Supplies

Use a 24VDC power supply for both relay and transistor outputs.

- Connect the "positive" lead to the "V1" terminal, and the "negative" lead to the "0V" terminal.
- In the event of voltage fluctuations or nonconformity to voltage power supply specifications, connect the device to a regulated power supply.



### Relay Outputs

- Each group can be wired separately to either AC or DC as show.
- The 0V signal of the relay outputs is isolated from the controller's 0V signal.



### Increasing Contact Life Span

To increase the life span of the relay output contacts and protect the device from potential damage by reverse EMF, connect:

- a clamping diode in parallel with each inductive DC load,
- an RC snubber circuit in parallel with each inductive AC load.



### **Transistor Outputs**

- Each output can be wired separately as either npn or pnp.
- The 0V signal of the transistor outputs is isolated from the controller's 0V signal.



# **Analog Inputs**

5 analog inputs:

- Inputs 0 to 2 can be wired to work with either current or voltage.
- Inputs 3 and 4 can function as either analog, RTD, or thermocouple, when appropriately wired as shown in the following figures.

To configure an input, open the device and set the jumpers according to the instructions beginning on page 8. Shields should be connected at the signal source.

### **Analog Inputs**

 When set to current/voltage, all inputs share a common ACM signal, which must be connected to the 0V of the controller.



### **RTD Inputs**

- PT100 (Sensor 3): use both inputs related to CM3 signal.
- PT100 (Sensor 4): use both inputs related to CM4 signal.
- 4 wire PT100 can be used by leaving one of the sensor leads unconnected.



# **Thermocouple Inputs**

- Supported thermocouple types include B, E, J, K, N, R, S, and T, in accordance with software and jumper settings. See table, Thermocouple Input Ranges, on page 15.
- Inputs may be set to mV by software settings (Hardware Configuration); note that in order to set mV inputs, thermocouple jumper settings are used.
- To ensure proper performance, a warm-up period of a half an hour is recommended.



# **Analog Outputs Power Supply**

Use a 24VDC power supply for all analog output modes.

- 1. Connect the "positive" cable to the "V2" terminal, and the "negative" to the "0V" terminal.
- In the event of voltage fluctuations or non-conformity to voltage power supply specifications, connect the device to a regulated power supply.
- Since the analog I/O power supply is isolated, the controller's 24VDC power supply may also be used to power the analog I/Os.

The 24VDC power supply must be turned on and off simultaneously with the controller's power supply.



# **Analog Outputs**

- Shields should be earthed, connected to the earth of the cabinet.
- An output can be wired to either current or voltage, use the appropriate wiring as shown below.
- Do not use current and voltage from the same source channel.





# **Changing Jumper Settings**

To access the jumpers, you must remove the snap-in I/O module from the controller, and then remove the module's PCB board.

- Before you begin, turn off the power supply, disconnect and dismount the controller.
- Before performing these actions, touch a grounded object to discharge any electrostatic charge.
  - Avoid touching the PCB board directly by holding the PCB board by its connectors.

# Accessing the Jumpers

First, remove the snap-in module.

- Locate the 4 buttons on the sides of the module, 2 on either side. Press the 2 buttons on either side of the module as shown, and hold them down to open the locking mechanism.
- 2. Gently rock the module from side to side, easing the module from the controller.



3. Using a Philips screwdriver, remove the center screw from the module's PCB board.



Select the desired function by changing the jumper settings according to the figure and tables shown below.

	Jumper #	Voltage*	Current
Analog input 0	3	V	Ι
Analog input 1	2	V	I
Analog input 2	1	V	Ι

	Jumper #	Voltage*	Current	T/C or mV	PT100
Analog input 3	5	AN	AN	PT-TC	PT-TC
	7	V	Ι	V	V
Analog input 4	4	AN	AN	PT-TC	PT-TC
	6	V	I	V	V

\* Default factory setting

9

- 1. Return the PCB board to the module and secure the center screw.
- 2. Next, reinstall the module. Line the circular guidelines on the controller up with the guidelines on the Snap-in I/O Module as shown below.
- 3. Apply even pressure on all 4 corners until you hear a distinct 'click'. The module is now installed. Check that all sides and corners are correctly aligned.



# V200-18-E6B Technical Specifications

Digital Inputs	
Number of inputs	18 (in two groups)
Input type	pnp (source) or npn (sink)
Galvanic isolation	
Digital inputs to bus	Yes
Digital inputs to digital inputs in same group	No
Group to group, digital inputs	Yes
Nominal input voltage	24VDC
Input voltage	
pnp (source)	0-5VDC for Logic '0' 17-28.8VDC for Logic '1'
npn (sink)	17-28.8VDC for Logic '0' 0-5VDC for Logic '1'
Input current	6mA@24VDC for inputs 4 to 17 8.8mA@24VDC for inputs 0 to 3
Response time	10mSec typical
High-speed inputs	Specifications below apply when these inputs are wired for use as a high- speed counter input/shaft encoder. See Notes 1 and 2.
Resolution	32-bit
Frequency	10kHz maximum
Minimum pulse width	40µs

# Notes:

- Inputs 0 and 2 can each function as either high-speed counter or as part of a shaft encoder. In each case, high-speed input specifications apply. When used as a normal digital input, normal input specifications apply.
- Inputs 1 and 3 can each function as either counter reset, or as a normal digital input; in either case, its specifications are those of a normal digital input. These inputs may also be used as part of a shaft encoder. In this case, high-speed input specifications apply.

### Digital Outputs

### **Digital Output's Power Supply**

Nominal operating voltage	24VDC
Operating voltage	20.4 to 28.8VDC
Quiescent current	5mA@24VDC.
Max. current consumption	85mA@24VDC. See Note 3
Galvanic isolation	
Digital power supply to bus	Yes
Digital power supply to relay outputs	Yes
Digital power supply to transistor outputs	No

### Notes:

3. Maximum current consumption does not provide for pnp output requirements. The additional current requirement of pnp outputs must be added.

Relay Outputs	
Number of outputs	15 relays (in two groups). See Note 4.
Output type	SPST-NO (Form A)
Isolation	By relay
Type of relay	Tyco PCN-124D3MHZ or compatible
Outputs' power supply	See Digital Output's Power Supply page 11.
Galvanic isolation	
Relay outputs to bus	Yes
Group to group, relay outputs	Yes
Relay to transistor outputs	Yes
Output current	3A maximum per output (resistive load) 8A maximum total for common (resistive load)
Rate voltage	250VAC / 30VDC
Minimun load	1mA@5VDC
Life expectancy	100k operations at maximum load
Response time	10mS (typical)
Contact protection	External precautions required (see Increasing Contact Life Span, p.4)

# Notes:

4. Outputs 2, 3, 4, 5, 6 and 7 share a common signal. Outputs 8, 9, 10, 11, 12, 13, 14, 15 and 16 share a common signal.

# Transistor Outputs/H.S.O.

Number of outputs	2, high-speed. Each can be individually wired as pnp (source) or npn (sink).
Output type	pnp: P-MOSFET (open drain) npn: N-MOSFET (open drain)
Galvanic isolation	
Transistor outputs to bus	Yes
Transistor outputs to transistor outputs	No
Transistor outputs to relay outputs	Yes
Output current	pnp: 0.5A maximum per output
	npn: 50mA maximum per output
Maximum frequency	Resistive load pnp: 0.5kHz non: 50kHz
	Inductive load 0.5Hz
ON voltage drop	pnp: 0.5VDC maximum npn: 0.4VDC maximum
Short circuit protection	Yes (pnp only)
Voltage reference	
pnp (source)	See Digital Output's Power Supply page 11
npn (sink)	3.5V to 28.8VDC, unrelated to the voltage of either the I/O module or the controller

Analog/RTD/TC Inputs			
Number of inputs	5		
Type of input	Set via appropriate wiring and jumper settings. See Note 5.		
Isolation	None		
Analog Inputs			
	AN0-AN2 (10-bit)	AN3-AN4 (14-bit)	
Input range	0-10V, 0-20mA , 4-20mA	0-10V, 0-20mA , 4-20mA	
Conversion method	Succesive approximation	Voltage to frequency	
Normal mode			
Resolution, except 4-20mA	10-bit (1024 units)	14-bit (16384 units)	
Resolution at 4-20mA	204-1023 (820 units)	3277 to 16384 (13107 units)	
Conversion time	Synchronized to scan time	100mSec minimum per input (according to filter type)	
Fast Mode			
Resolution, except 4-20mA	_	12-bit (4096 units)	
Resolution at 4-20mA	_	819 to 4095 (3277 units)	
Conversion time	-	30mSec minimum per input (according to filter type)	
Input impedance	>100kΩ—voltage	12.77kΩ —voltage	
	500Ω—current	37Ω —current	
Absolute maximum rating	±15V—voltage	±15V—voltage	
	±30mA, 15V—current	±30mA, 1.1V—current	
Full-scale error	±3 LSB (0.3%)	±0.4%	
Linearity error	±3 LSB (0.3%)	±0.04%	
Status indication	Yes. See Note 6.	Yes. See Note 7.	

# Notes:

Inputs 0 to 2 may be wired to work with either current or voltage. 5.

Value: 10-bit

1024

Inputs 3 and 4 can function as either analog, RTD, or thermocouple.

The analog value can indicate a fault: 6.

# Possible Cause

Deviates above the input range

7. The analog value can indicate faults:

Value: 12-bit	Value: 14-bit		
-1	-1		
4096	16384		
32767	32767		

# Possible Cause

Deviates slightly below the input range Deviates slightly above the input range Deviates greatly above or below the input range

### V200-18-E6B Snap-in I/O Module

# **RTD** Inputs

•	
Input range	-200 to 600°C/-328 to 1100°F. 1 to 320Ω. See Note 8.
RTD type	PT100
Temperature coefficient α	385/392
Conversion method	Voltage to frequency
Resolution	0.1°C/0.1°F
Conversion time	300mS minimum per channel, depending on software filter type
Input impedance	>10MΩ
Auxillary current for PT100	150μA typical
Full-scale error	±0.4%
Linearity error	±0.04%
Status indication	Yes. See Note 9.

#### Notes:

- 8. The device can also measure resistance with the range of  $1-320\Omega$  at a resolution of  $0.1\Omega$ .
- 9. The analog value can indicate faults:

### Value Possible Cause

32767 Sensor is not connected to input, or value exceeds permissible range -32767 Sensor is short-circuited

Thermocouple Inputs	
Input range	See Note 10.
Conversion method	Voltage to frequency
Resolution	0.1°C/0.1°F maximum
Conversion time	100mS minimum per channel, depending on software filter type
Input impedance	>10MΩ
Cold junction compensation	Local, automatic
Cold junction compensation error	±1.5°C/±2.7°F maximum
Absolute maximum rating	±0.6VDC
Full-scale error	±0.4%
Linearity error	±0.04%
Warm-up time	1/2 hour typically, ±1°C/±1.8°F repeatability
Status indication	None

### Notes:

10. The device can also measure voltage within the range of -5 to 56mV, at a resolution of 0.01mV. The device can also measure raw value frequency at a resolution of 14-bits (16384). Input ranges are shown in the following table:

Table 1: Thermocouple input ranges			
Туре	Temperature range	Wire Color	
		ANSI (USA)	BS 1843 (UK)
mV	-5 to 56mV	-	-
В	200 to 1820°C	+Grey	+None
	(300 to 3276°F)	-Red	-Blue
E	-200 to 750°C	+Violet	+Brown
	(-328 to 1382°F)	-Red	-Blue
J	-200 to 760°C	+White	+Yellow
	(-328 to 1400°F)	-Red	-Blue
K	-200 to 1250°C	+Yellow	+Brown
	(-328 to 2282°F)	-Red	-Blue
Ν	-200 to 1300°C	+Orange	+Orange
	(-328 to 2372°F)	-Red	-Blue
R	0 to 1768°C	+Black	+White
	(32 to 3214°F)	-Red	-Blue
S	0 to 1768°C	+Black	+White
	(32 to 3214°F)	-Red	-Blue
Т	-200 to 400°C	+Blue	+White
	(-328 to 752°F)	-Red	-Blue

# Analog Outputs

Anal	og	Out	tpuť	s P	ower	Supp	ly
------	----	-----	------	-----	------	------	----

Nominal operating voltage	24VDC
Operating voltage	20.4 to 28.8VDC
Quiescent current	30mA@24VDC
Max. current consumption	80mA@24VDC
Galvanic isolation	
Analog power supply to bus	Yes
Analog power supply to analog outputs	No
Analog Outputs	
Number of outputs	2 (single-ended)
Output range	0-10V, 4-20mA. See Note 11.
Resolution	12-bit (4096 units)
Conversion time	Synchronized to scan time
Load impedance	1kΩ minimum—voltage
	500Ω maximum—current
Galvanic isolation	
Analog outputs to bus	Yes
Analog output to analog output	No
Linearity error	±0.1%
Operational error limits	±0.2%
Notes:	
11. Note that the range of each I/O is	defined by wiring and within the controller's software.
<u>Environmental</u>	IP20 / NEMA1
Operating temperature	0° to 50°C (32° to 122°F)
Storage temperature	-20° to 60°C (-4° to 140°F)
Relative Humidity (RH)	10% to 95% (non-condensing)
Dimensions (WxHxD)	138x23x123mm (5.43x0.9x4.84")
Weight	140g (4.94oz)

## **About Unitronics**

Unitronics has been producing PLCs, automation software and accessory devices since 1989.

Unitronics' OPLC controllers combine full-function PLCs and HMI operating panels into single, compact units. These HMI + PLC devices are programmed in a single, user-friendly environment. Our clients save I/O points, wiring, space, and programming time; elements that translate directly into cost-efficiency.

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